Tuesday 25 October 2016

1 Linear Regression

We make a bit of a shift of topic now, from statistical tests and confidence intervals to the process of fitting data to a model. The techniques will seem rather different, but it’s enlightening to make contact with what we’ve done before.

Recall that in our treatment of paired data, we considered data sets \( \{x_i | i = 1, \ldots, n\} \) and \( \{y_i | i = 1, \ldots, n\} \) which were assumed to drawn from joint distributions where \( X_i \) and the corresponding \( Y_i \) were correlated (for instance a bivariate normal distribution), and we drew inferences on the statistical properties of

\[
D_i = X_i - Y_i
\] (1.1)

We can write this relationship as

\[
Y_i = X_i + D_i
\] (1.2)

Note, however, that the distributions for \( X_i \) and \( D_i \) are in general correlated,

\[
\text{Cov}(X_i, D_i) = \text{Var}(X_i) - \text{Cov}(X_i, Y_i)
\] (1.3)

If the underlying distribution was a bivariate Gaussian, we’d expect the data to be spread out roughly in an ellipse in the \( x\)-\( y \) plane:
Note that this has a lot more structure than is reflected in just $\mu_D = \mu_1 - \mu_2$.

In the case of linear regression, we want to consider data which are once again paired into $x_i, y_i$, but now the model we assume is that $y_i$ is a linear function of $x_i$ plus some error whose properties don’t depend on $x_i$. In terms of random variables, this means

$$Y_i = \beta_0 + \beta_1 X_i + \epsilon_i$$

where $\beta_0$ and $\beta_1$ are constants, and $\epsilon_i$ follows a distribution which is independent of $X_i$; for concreteness we will assume $\epsilon_i \sim N(0, \sigma^2)$ where the error amplitude $\sigma$ is some non-negative constant. It is also conventional to assume that the values \{x_i\} are known constants, and thus write

$$Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

although the data analysis is the same in any event. Data associated with a linear regression model are typically spread out about a diagonal line, with the typical offset values being the same all along the line:

### 1.1 Estimation of Parameters

The first task to be performed in a linear regression problem is to estimate the parameters $\beta_0$ and $\beta_1$, as well as the error amplitude $\sigma$. The usual method for the slope $\beta_1$ and intercept $\beta_0$ is known as least squares, which finds the values which minimize

$$q(\beta_0, \beta_1) = \sum_{i=1}^{n} (y_i - \beta_0 - \beta_1 x_i)^2$$

This seems a bit ad hoc at first, and in fact it appears unconnected to our previous method because the techniques of regression and least squares estimation predate the development of classical statistics. But we can actually motivate the process by
a standard technique: maximum likelihood estimation. For a
given \( x_i, Y_i \sim N(\beta_0 + \beta_1 x_i, \sigma^2) \), which means the pdf is
\[
f_i(y_i; \beta_0, \beta_1, \sigma) = \frac{1}{\sigma \sqrt{2\pi}} \exp\left(-\frac{(y_i - \beta_0 - \beta_1 x_i)^2}{2\sigma^2}\right)
\]
and the log-likelihood is
\[
\ln f(y_1, \ldots, y_n; \beta_0, \beta_1, \sigma) = \sum_{i=1}^{n} \ln f_i(y_i) = \sum_{i=1}^{n} \ln f_i(y_i)
= -n/2 \ln(2\pi) - n \ln \sigma - \frac{1}{2\sigma^2} \sum_{i=1}^{n} (y_i - \beta_0 - \beta_1 x_i)^2
\]
For any value of \( \sigma \), then, the \( \beta_0 \) and \( \beta_1 \) values which maximize
the likelihood will be those which minimize \( q(\beta_0, \beta_1) \). The partial
derivatives are
\[
\frac{\partial q}{\partial \beta_0} = -2 \sum_{i=1}^{n} (y_i - \beta_0 - \beta_1 x_i)
\]
\[
\frac{\partial q}{\partial \beta_1} = -2 \sum_{i=1}^{n} x_i(y_i - \beta_0 - \beta_1 x_i)
\]
and setting both to zero gives the system of equations for the
maximum likelihood estimates \( \hat{\beta}_0 \) and \( \hat{\beta}_1 \):
\[
\sum_{i=1}^{n} x_i \hat{\beta}_0 + \left( \sum_{i=1}^{n} x_i \right) \hat{\beta}_1 = \sum_{i=1}^{n} y_i
\]
\[
\left( \sum_{i=1}^{n} x_i \right) \hat{\beta}_0 + \left( \sum_{i=1}^{n} x_i^2 \right) \hat{\beta}_1 = \sum_{i=1}^{n} x_i y_i
\]
which can also be written
\[
\hat{\beta}_0 + x \hat{\beta}_1 = \bar{y}
\]
\[
x \hat{\beta}_0 + x^2 \hat{\beta}_1 = x \bar{y}
\]
and has solutions
\[
\hat{\beta}_1 = \frac{\bar{y} - \bar{x} \bar{y}}{\bar{x}^2 - (\bar{x})^2}
\]
\[
\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}
\]
Note that the second expression for \( \hat{\beta}_1 \) is less prone to round-
off errors, but the first can be easily computed using the first
and second moments of the data \( n, \sum_{i=1}^{n} x_i, \sum_{i=1}^{n} y_i, \sum_{i=1}^{n} x_i^2,
\sum_{i=1}^{n} y_i^2, \) and \( \sum_{i=1}^{n} x_i y_i \) as long as extra precision is kept in
intermediate steps. For any \( x \), we can generate a point estimate
of the corresponding \( y \), i.e., \( \hat{\beta}_0 + \hat{\beta}_1 x \). In particular, for \( x_i \) the
corresponding “predicted” value is \( \hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i \), and we call
\( y_i - \hat{y}_i \) the residual.

We can return now to the question of estimating \( \sigma \). One
obvious point estimate would be the maximum likelihood value;
setting the partial derivative of \( \ln f \)
to zero would give a maximum likelihood estimate of \( \sigma^2 \) equal
to
\[
\frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i)^2 = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2
\]
however, as with the case for the mle of \( \sigma^2 \) from a normal random
sample, this turns out to be a biased estimator because we have
to estimate the two parameters \( \beta_0 \) and \( \beta_1 \) from the data. The
unbiased estimator is
\[
\hat{\sigma}^2 = s^2 = \frac{1}{n-2} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2 = \frac{\text{SSE}}{n-2}
\]
where we have defined the sum square error (SSE) associated with the estimates \( \{ \hat{y}_i \} \). A little bit of algebraic manipulation shows that we can also calculate this as

\[
\text{SSE} = \sum_{i=1}^{n} y_i^2 - \hat{\beta}_0 \sum_{i=1}^{n} y_i - \hat{\beta}_1 \sum_{i=1}^{n} x_i y_i
\]  

(1.16)

Sometimes it’s useful to quantify how much of the variability of the \( \{ y_i \} \) is explained by the best-fitting linear model. We note that \( \text{SSE} = q(\hat{\beta}_0, \hat{\beta}_1) \) is the lowest possible value of \( q(\beta_0, \beta_1) \).

If we instead restricted ourselves to models with \( \beta_1 = 0 \), i.e., assumed that \( \{ y_i \} \) was a sample from a normal distribution \( N(\beta_0, \sigma^2) \), we would find that the best fitting value for \( \beta_0 \) was \( \bar{y} \) and therefore the lowest value of \( q(\beta_0, 0) \) is

\[
q(\bar{y}, 0) = \frac{1}{n} \sum_{i=1}^{n} (y_i - \bar{y})^2 = \text{SST} = \sum_{i=1}^{n} y_i^2 - \frac{1}{n} \left( \sum_{i=1}^{n} y_i \right)^2
\]  

(1.17)

This is called the SST or total sum of squares, and it is a measure of the deviation of the points from the best-fitting horizontal line (whereas the SSE is the deviation from the best-fitting diagonal line). Since \( q(\beta_0, \beta_1) \) as defined is always non-negative, and the SSE is the lowest possible value of the function, we have

\[
0 \leq \text{SSE} \leq \text{SST}
\]  

(1.18)

The ratio \( \text{SSE}/\text{SST} \) can thus be used to measure how important it was to use a diagonal rather than a horizontal line for the fit. If it’s close to 1, then a horizontal line fits almost as well; if it’s close to 0, then the diagonal line gives a much better fit. We define the coefficient of determination

\[
r^2 = 1 - \frac{\text{SSE}}{\text{SST}}
\]  

(1.19)

as a measure \( (0 \leq r^2 \leq 1) \) of how much better the diagonal line fits than the horizontal line.

Practice Problems

12.9, 12.11, 12.17, 12.19

Thursday 27 October 2016

1.2 Inference for the Slope Parameter

So far, we’ve considered point estimates for the parameters \( \beta_0 \), \( \beta_1 \) and \( \sigma^2 \), which were

\[
\hat{\beta}_1 = \frac{\sum_{i=1}^{n} (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^{n} (x_i - \bar{x})^2} 
\]  

(1.20)

\[
\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}
\]  

(1.21)

and

\[
s^2 = \frac{1}{n - 2} \sum_{i=1}^{n} (y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i)^2
\]  

(1.22)

respectively. Now we turn to interval estimation and hypothesis testing. We’ll focus on the slope parameter \( \beta_1 \), and consider the statistical properties of the estimator

\[
\hat{\beta}_1 = \frac{\sum_{i=1}^{n} (x_i - \bar{x})(Y_i - \bar{Y})}{\sum_{i=1}^{n} (x_i - \bar{x})^2}
\]  

(1.23)

Note that since we’re treating the \( \{ x_i \} \) as given, the only randomness associated with the estimator comes from the \( \{ Y_i \} \). Also, note that

\[
\sum_{i=1}^{n} (x_i - \bar{x})Y_i = \bar{Y} \left( \sum_{i=1}^{n} x_i - n\bar{x} \right) = 0
\]  

(1.24)

so

\[
\hat{\beta}_1 = \frac{\sum_{i=1}^{n} (x_i - \bar{x})Y_i}{S_{xx}}
\]  

(1.25)
where \( S_{xx} = \sum_{i=1}^{n}(x_i - \bar{x})^2 \). (Note that despite being written with a capital letter, \( S_{xx} \) is not a statistic or other random variable.) Since \( Y_i \sim N(\beta_0 + \beta_1 x_i, \sigma^2) \), \( \hat{\beta}_1 \), which is a linear combination of the independent normal random variables \( \{Y_i\} \), is normal with

\[
E(\hat{\beta}_1) = \sum_{i=1}^{n}(x_i - \bar{x})(\beta_0 + \beta_1 x_i) = \beta_1
\]

and

\[
V(\hat{\beta}_1) = \sum_{i=1}^{n}(x_i - \bar{x})^2\sigma^2 = \sigma^2 S_{xx} = \sigma^2 \]

To make a standardized statistic, we have to estimate \( \sigma \hat{\beta}_1 = \sigma/\sqrt{S_{xx}} \) using the estimate \( s \) in place of \( \sigma \). Specifically,

\[
S_{\hat{\beta}_1}^2 = \frac{S^2}{S_{xx}} = \frac{1}{(n-2)S_{xx}} \sum_{i=1}^{n}(Y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i)^2
\]

Since the variance estimate required the estimation of two parameters, the standardized statistic

\[
T = \frac{\hat{\beta}_1 - \beta_1}{S_{\hat{\beta}_1}} = \frac{\hat{\beta}_1 - \beta_1}{\sqrt{S^2/S_{xx}}}
\]

obeys a Student t distribution with \( n - 2 \) degrees of freedom.

We can apply this as usual; as a pivot variable, it gives us a confidence interval at \( CL = (1 - \alpha) \times 100\% \) with endpoints

\[
\hat{\beta}_1 \pm t_{\alpha/2,n-2} s/\sqrt{S_{xx}}
\]

Similarly, if we want to test a hypothesis \( H_0 \) which says \( \beta_1 = \beta_1^{(0)} \) for some proposed value \( \beta_1^{(0)} \), the test statistic is

\[
t = \frac{\hat{\beta}_1 - \beta_1^{(0)}}{s/\sqrt{S_{xx}}}
\]

which we compare to \( t_{\alpha,n-2} \), \(-t_{\alpha,n-2} \) or \( \pm t_{\alpha/2,n-2} \), depending on whether it’s appropriate to carry out an upper-, lower-, or two-tailed test.

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**Practice Problems**

12.31, 12.79

**Tuesday 1 November 2016**

### 1.3 Inferences about Predicted Values

#### 1.3.1 Confidence Interval for Average Model Value

Reminder of the linear regression model: Treating the \( \{x_i\} \) as given, the observed data are independent rvs, with

\[
Y_i \sim N(\beta_0 + \beta_1 x_i, \sigma^2)
\]

where \( \beta_0, \beta_1 \) and \( \sigma \) are treated as unknown variables. The maximum likelihood/least squares estimators of \( \beta_1 \) and \( \beta_0 \) are

\[
\hat{\beta}_1 = \frac{S_{xy}}{S_{xx}} = \frac{1}{S_{xx}} \sum_{i=1}^{n}(x_i - \bar{x})Y_i
\]

and

\[
\hat{\beta}_0 = \bar{Y} - \bar{x}\hat{\beta}_1
\]

We’ve seen (between class and homework) that \( \hat{\beta}_0 \) and \( \hat{\beta}_1 \) are each normally distributed unbiased estimators of the corresponding parameter. But rather than just placing confidence intervals on the slope and intercept of the linear function giving the expectation value of the data as a function of \( x \), we’re often interested in the uncertainty of where that line is at each point. I.e., we’d like to estimate the quantity \( \beta_0 + \beta_1 x \) for a given \( x \). Devore refers to the \( x \) value of interest as \( x^* \), and the quantity of interest as

\[
\mu_{Y|x^*} = \beta_0 + \beta_1 x^*
\]
The obvious estimator is
\[ \hat{\beta}_0 + \hat{\beta}_1 x^* = \bar{Y} + \hat{\beta}_1 (x^* - \bar{x}) = \sum_{i=1}^{n} \left( \frac{1}{n} + \frac{(x^* - \bar{x})(x_i - \bar{x})}{S_{xx}} \right) Y_i \]
(1.36)
which Devore calls \( \hat{Y} \). Since it’s a linear combination of the \{Y_i\}, it’s a normally-distributed random variable. As a statistic, it has expectation value
\[ E(\hat{Y}) = E(\hat{\beta}_0) + E(\hat{\beta}_1) x^* = \beta_0 + \beta_1 x^* = \mu_{Y \cdot x^*} \]
(1.37)
I.e., it’s an unbiased estimator. Since the \{Y_i\} are independent random variables, the variance is
\[ V(\hat{Y}) = \sum_{i=1}^{n} \left( \frac{1}{n} + \frac{(x^* - \bar{x})(x_i - \bar{x})^2}{S_{xx}} \right)^2 V(Y_i) = \sigma^2 \left( \frac{1}{n} + \frac{(x^* - \bar{x})^2}{S_{xx}} \right) \]
(1.38)
(We’ve omitted several steps of non-trivial algebra at the last equals sign!)
As usual, we can’t actually calculate \( V(\hat{Y}) \) from the data; we have to estimate it by replacing \( \sigma^2 \) with
\[ s^2 = \frac{\text{SSE}}{n-2} = \frac{1}{n-2} \left( S_{yy} - \frac{S_{2y}^2}{S_{xx}} \right) \]
(1.39)
and thus writing
\( s_Y = s \sqrt{\frac{1}{n} + \frac{(x^* - \bar{x})^2}{S_{xx}}} \)
(1.40)
We then know that
\[ T = \frac{\hat{Y} - \mu_{Y \cdot x^*}}{s_Y} \]
(1.41)
is a Student-\( t \) distributed random variable with \( n - 2 \) degrees of freedom. So for example if we want a confidence interval at confidence level \( \alpha \) on \( \beta_0 + \beta_1 x^* \) it will be
\[ \hat{\beta}_0 + \hat{\beta}_1 x^* \pm t_{\alpha/2, n-2} \ s \ \sqrt{\frac{1}{n} + \frac{(x^* - \bar{x})^2}{S_{xx}}} \]
(1.42)
Note that the width of this confidence interval depends on \( x^* \). It is a minimum for \( x^* = \bar{x} \), and grows as \( x^* \) gets farther away from \( \bar{x} \). This reflects the fact that, the farther we get from the middle of the data used to estimate the linear relationship between \( x \) and \( y \), the less accurately we can estimate the best-fit line.
reflected in our uncertainty on $\beta_0$ and $\beta_1$. (Our model doesn’t include a $\beta_2$, $\beta_3$, etc, so we’re assuming they’re zero, but we don’t quantify our uncertainty on that.)

1.3.2 Prediction Intervals for Future Values

Now we wish to consider a slightly different question. Suppose, after making observations of $n$ random variables $\{Y_i\}$ where $Y_i \sim N(\beta_0 + \beta_1 x_i, \sigma^2)$ and doing linear regression estimating using the values $\{y_i\}$, we take a new value $Y$ at $x^*$. (You could think of this as $Y_{n+1}$ if you like, in which case $x^*$ would be $x_{n+1}$.) The best estimator we can use for $Y$, constructed from previous $\{Y_i\}$, is $\hat{Y}$, defined above. Since

$$E(Y) = E(\hat{Y}) = \mu_{Y, x^*} \quad (1.43)$$

the statistic $Y - \hat{Y}$ has zero expectation value. Since $\hat{Y}$ is constructed only from the previous $\{Y_i\}$, $Y$ and $\hat{Y}$ are independent random variables, and thus

$$V(Y - \hat{Y}) = V(Y) + (-1)^2 V(\hat{Y}) = \sigma^2 + \sigma^2_{\hat{Y}} = \sigma^2 \left( 1 + \frac{1}{n} + \frac{(x^* - \bar{x})^2}{S_{xx}} \right) \quad (1.44)$$

Thus we see the prediction interval is wider than the confidence interval for the random variable, since it includes the inherent uncertainty associated with each measurement as well as the uncertainty in determining the best-fit line itself.

Practice Problems

12.45, 12.53

Thursday 3 November 2016

Review for Prelim Exam Two (from section 8.3 to 12.3, inclusive). Please bring questions, and ideally ask them by email before class.

Tuesday 8 November 2016

Prelim Exam Two (from section 8.3 to 12.3, inclusive). Closed book, closed notes, but you may bring one handwritten 8.5”×11” (front and back) formula sheet, and also use a scientific calculator.
1.4 Residuals

(See Devore Section 13.1)

Recall that in our simple linear regression model, we are assuming that $Y_1, Y_2, \ldots, Y_n$ are independent random variables with

$$Y_i \sim N(\beta_0 + \beta_1 x_i, \sigma^2)$$  \hfill (1.45)

where $\beta_0, \beta_1$ and $\sigma$ are unknown. The best-fit estimates $\hat{\beta}_0$ and $\hat{\beta}_1$ from the $\{x_i\}$ and the observed $\{y_i\}$. The point estimate of the expected $y$ value at any $x$ is thus $\hat{\beta}_0 + \hat{\beta}_1 x$. In particular, the best-fit model value at $x_i$ is

$$\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$$  \hfill (1.46)

Of course, this is not equal to the actual $y_i$, so it is useful to plot $e_i = y_i - \hat{y}_i$. According to our statistical model,

$$E(\hat{y}_i) = E(\hat{\beta}_0) + E(\hat{\beta}_1) x_i = \beta_0 + \beta_1 x_i = E(Y_i)$$

so $E(Y_i - \hat{y}_i) = 0$. We also know $V(Y_i) = \sigma^2$ and, from last time,

$$V(\hat{y}_i) = \sigma^2 \left( \frac{1}{n} + \frac{(x_i - \bar{x})^2}{S_{xx}} \right)$$  \hfill (1.48)

However, there is one complication in working out $V(E_i) = V(Y_i - \hat{y}_i)$, which is that, since $\hat{y}_i$ is constructed using the estimators $\hat{\beta}_0$ and $\hat{\beta}_1$, which are in turn constructed from all of the random variables $\{Y_1, Y_2, \ldots, Y_n\}$, the rvs $Y_i$ and $\hat{y}_i$ are not independent. (Compare this to the situation with prediction intervals, where the value being considered was a new $Y$ (or $Y_{n+1}$, not included in the original set.) The variance of the residual is thus, when you work out the form of the covariance between

$$V(E_i) = V(Y_i - \hat{y}_i) = V(Y_i) + V(\hat{y}_i) - 2 \text{Cov}(Y_i, \hat{y}_i)$$

$$= \sigma^2 \left( 1 - \frac{1}{n} - \frac{(x_i - \bar{x})^2}{S_{xx}} \right)$$  \hfill (1.49)

Note that this is smaller than $\sigma^2$, and gets smaller when $x_i$ is farther from the mean of the $x$s. This is because the data themselves are pulling the best fit line towards them, and so even if there are big fluctuations, those fluctuations will influence the best-fit model.

One can plot the standardized residuals

$$e^*_i = \frac{y_i - \hat{y}_i}{s \sqrt{1 - \frac{1}{n - \frac{(x_i - \bar{x})^2}{S_{xx}}}}}$$  \hfill (1.50)

and see if they are indeed Student-$t$ distributed with $n - 2$ degrees of freedom.

2 Correlation

(See Devore Section 12.5)

Finally, we consider a situation where the picture, at least in terms of classical statistics, is different from the regression formalism, but the formulas are related. We’ve been assuming the $\{x_i\}$ were just given numbers and the $\{Y_i\}$ were random variables with realizations $\{y_i\}$. We could also imagine that the $\{x_i\}$ themselves were the realizations of random variables $\{X_i\}$

The rvs are not all independent, but we assume that $\{X_i, Y_i\}$ is a sample drawn from a bivariate distribution, which means that (if the distribution is continuous) the joint pdf is

$$f(x_1, \ldots, x_n, y_1, \ldots, y_n) = f(x_1, y_1) f(x_2, y_2) \cdots f(x_n, y_n)$$  \hfill (2.1)

We will now see that a quantity defined in the context of regression actually has a familiar interpretation when considered in the bivariate context.

\footnote{This is largely a “distinction without a difference” because the standard regression treatment works if you consider all of the distributions for $Y_i$ to be conditional distributions for a given realization of $\{x_i\}$, i.e., $f_{Y_i|x_i}(y_i)$ is actually $f_{Y|x}(y_i|x_i).$}
Recall the coefficient of determination \( r^2 \), defined as

\[
\begin{align*}
\frac{SSE}{SST} &= 1 - \frac{1}{S_{yy}} \left( S_{yy} - \frac{S_{xy}^2}{S_{xx}} \right) = \frac{S_{xx}S_{yy} - S_{xx}S_{yy} + S_{xy}^2}{S_{xx}S_{yy}} \\
&= \frac{S_{xy}^2}{S_{xx}S_{yy}} \quad (2.2)
\end{align*}
\]

so that \( 0 \leq r^2 \leq 1 \). Now, \( S_{xx} \) and \( S_{yy} \) are both positive, but \( S_{xy} \) need not be. So we can define

\[
r = \frac{S_{xy}}{\sqrt{S_{xx}S_{yy}}} \quad (2.3)
\]

This is called the sample correlation coefficient, and obviously the square of \( r \) is the coefficient of determination, which we’ve already called \( r^2 \). If we recall the definition of the sample variances

\[
\begin{align*}
s_x^2 &= \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \overline{x})^2 = \frac{S_{xx}}{n-1} \quad (2.4a) \\
s_y^2 &= \frac{1}{n-1} \sum_{i=1}^{n} (y_i - \overline{y})^2 = \frac{S_{yy}}{n-1} \quad (2.4b)
\end{align*}
\]

we see that

\[
rs_x s_y = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \overline{x})(y_i - \overline{y}) = \frac{S_{xy}}{n-1} \quad (2.5)
\]

This bears a striking similarity to the formulas for the variance, covariance and correlation of a pair of random variables:

\[
\begin{align*}
\sigma_x^2 &= V(X) = E([X - \mu_X]^2) \quad (2.6a) \\
\sigma_y^2 &= V(Y) = E([Y - \mu_Y]^2) \quad (2.6b) \\
\rho \sigma_x \sigma_y &= \text{Cov}(X,Y) = E([X - \mu_X][Y - \mu_Y]) \quad (2.6c)
\end{align*}
\]

So it should not be too surprising that if we have a sample \( \{x_i, y_i\} \) drawn from a bivariate distribution \( f(x, y) \) or \( p(x, y) \), the sample correlation coefficient \( r \) will be an estimator for the population correlation coefficient \( \rho \). In terms of a random sample, we can refer to the statistic

\[
R = \frac{\sum_{k=1}^{n} (X_k - \overline{X})(Y_k - \overline{Y})}{\sqrt{\sum_{i=1}^{n} (X_i - \overline{X})^2 \sqrt{\sum_{j=1}^{n} (Y_j - \overline{Y})^2}}} \quad (2.7)
\]

where we’ve given the sum indices different labels to stress that there are three separate sums in the definition (not counting those used to define \( \overline{X} \) and \( \overline{Y} \)).

The sample correlation coefficient can be used as a statistic to perform inferences about the correlation present in the population. For simplicity, we’ll consider only the case of a hypothesis test where the null hypothesis is \( \rho = 0 \). In the case where the underlying distributions are both normal, symmetry tells us that \( E(R) = 0 \). It turns out (you’ll sort of show this on the homework) that

\[
T = \frac{R \sqrt{n-2}}{\sqrt{1 - R^2}} \quad (2.8)
\]

obeys a Student-\( t \) distribution with \( n-2 \) degrees of freedom.

**Practice Problems**

12.59, 12.83