

Physics A300: Classical Mechanics I

Problem Set 6

Assigned 2004 October 26
Due 2004 November 2

Show your work on all problems!

1 Work Done Along a Path

Consider the path parametrized by

$$x(s) = s x_0 \quad (1.1a)$$

$$y(s) = s y_0 \quad (1.1b)$$

$$z(s) = s z_0 \quad (1.1c)$$

where s ranges from 0 to 1. The position vector associated with this path is

$$\vec{r}(s) = \hat{x} x(s) + \hat{y} y(s) + \hat{z} z(s) \quad (1.2)$$

- What are the position vectors $\vec{r}(0)$ and $\vec{r}(1)$ of the endpoints of this path?
- Describe the path succinctly in words.
- Calculate the derivative $\frac{d\vec{r}}{ds}$ of the position vector with respect to the parameter.
- Suppose that a particle moves along this path while being acted on by a force field $\vec{F}(\vec{r})$ with components

$$F_x(x, y, z) = ay \quad (1.3a)$$

$$F_y(x, y, z) = ax + by^3 + cyz \quad (1.3b)$$

$$F_z(x, y, z) = bz^3 + cy^2z \quad (1.3c)$$

- Write the dot product $\vec{F}(\vec{r}(s)) \cdot \frac{d\vec{r}}{ds}$, using the trajectory (1.1) to substitute for x , y , and z and write your answer only as a function of s (and the constants a , b , c , x_0 , y_0 , and z_0).
- Calculate the work done by the force (1.3) on the particle as it moves along the path $\vec{r}(s)$ from $s = 0$ to $s = 1$. (Note that there must be other forces involved in the problem to keep the particle on this path, so Newton's second law is not really useful here.)

2 Velocity-Dependent Force in Three Dimensions

Consider a particle moving under the influence of the velocity-dependent force

$$\vec{F} = \vec{b} \times \vec{v} \quad (2.1)$$

where $\vec{b} = b\hat{z}$ is a constant vector.

- a) Writing the velocity as $\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$, work out the explicit form of \vec{F} in terms of b , v_x , v_y , v_z , and the unit vectors \hat{x} , \hat{y} , and \hat{z} .
- b) By considering the three components of Newton's Second Law $\vec{F} = m \frac{d\vec{v}}{dt}$, find explicit expressions for \dot{v}_x , \dot{v}_y and \dot{v}_z in terms of m , b , and the components of \vec{v} .
- c) The expressions you obtained in part b) are a set of coupled linear first-order differential equations for the three quantities $v_x(t)$, $v_y(t)$, and $v_z(t)$. The general solution will have a total of three arbitrary constants. You can solve them as follows:
 - i) Take the time derivative of the equation for \dot{v}_x to obtain an expression for \ddot{v}_x in terms of \dot{v}_y .
 - ii) Substitute the expression for \dot{v}_y from part b) into the equation for \ddot{v}_x . This should give you a second order linear differential equation involving only v_x and its derivatives.
 - iii) Find the general solution to the equation from part c)ii), which will give you an expression for v_x involving two arbitrary constants.
 - iv) Take the time derivative of the result from part c)iii) to obtain an expression for \dot{v}_x , substitute this into the left-hand side of the first differential equation from part b), and solve algebraically for v_y .
 - v) Solve the last differential equation from part b) to obtain an expression for v_z involving a third arbitrary constant.
- d) Suppose the particle has initial velocity $\vec{v}(0) = v_0 \hat{x}$. Use this initial condition to find the values of the three arbitrary constants in your general solution and write the form of $\vec{v}(t)$ in the presence of the force (2.1) given this initial condition.
- e) If the particle is initially at position $\vec{r}(0) = x_0 \hat{x} + y_0 \hat{y} + z_0 \hat{z}$, integrate the expressions for the components of $\vec{v}(t)$ to find the trajectory $\vec{r}(t) = x(t) \hat{x} + y(t) \hat{y} + z(t) \hat{z}$.

3 Conversion to Polar Coördinates

Converting a two-dimensional vector field from Cartesian to polar coördinates requires application not only of the coördinate transformations

$$x = r \cos \phi \quad (3.1a)$$

$$y = r \sin \phi \quad (3.1b)$$

but also the definitions of the basis vectors adapted to the two coördinate systems:

$$\hat{x} = \hat{r} \cos \phi - \hat{\phi} \sin \phi \quad (3.2a)$$

$$\hat{y} = \hat{r} \sin \phi + \hat{\phi} \cos \phi \quad (3.2b)$$

a) Show explicitly starting from (3.2) that

$$\hat{x} \cos \phi + \hat{y} \sin \phi = \hat{r} \quad (3.3a)$$

$$-\hat{x} \sin \phi + \hat{y} \cos \phi = \hat{\phi} \quad (3.3b)$$

b) Convert the following vector fields into polar coördinates. As an example, the vector field $\vec{F} = -kx \hat{x} - ky \hat{y}$ would be written $\vec{F} = -kr \hat{r}$.

i) $\vec{F} = -kx \hat{x}$

ii) $\vec{F} = -kx \hat{y} + ky \hat{x}$

iii) $\vec{F} = -\frac{\alpha}{x^2+y^2} (x \hat{x} + y \hat{y})$