# State of the Art MHD Methods for Astrophysical Applications

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### **Plan of Attack**

- Is NOT a survey of all possible methods!
- Highlight relatively new methods!
- Focus on tests and comparisons between the methods.
- Cover general idea of algorithms.
- Details are deferred to given references.

#### Outline

Introduction to ideal Relativistic MagnetoHydroDynamics (RMHD).

- Two basic approaches: Non-conservative and Conservative
- Methods for preserving the Divergence Constraint
- Conclusions

#### **Ideal Relativistic Magnetohydrodynamics**

Perfect fluid = Isotropic, inviscid, no thermal conductivity:

• 
$$T^{\mu\nu}_{\text{fluid}} = (P + \rho + \rho \epsilon) u^{\mu} u^{\nu} + P g^{\mu\nu}$$

• 
$$\nabla_{\mu} \left( \rho u^{\mu} \right) = \frac{1}{\sqrt{-g}} \partial_{\mu} \left( \sqrt{-g} \rho u^{\mu} \right) = 0$$

Electrically neutral, infinitely conducting fluid:

• 
$$T^{\mu\nu}_{\rm EM} = F^{\mu\alpha}F^{\nu}{}_{\alpha} - \frac{1}{4}g^{\mu\nu}F^{\alpha\beta}F_{\alpha\beta}$$

•  $\nabla_{\mu}F^{\mu\nu} = J^{\nu}$ 

• 
$$\nabla_{\mu}F^{*\mu\nu} = 0$$
 ,  $F^{*\mu\nu} = \frac{1}{2}\varepsilon_{\mu\nu\kappa\lambda}F^{\kappa\lambda}$ 

• Infinite conductance  $\Rightarrow F^{\mu\nu}u_{\mu} = 0$ 

$$F^{\mu\nu}u_{\mu} = 0 \qquad \nabla_{\mu}F^{*\mu\nu} = 0 \qquad \nabla_{\mu}F^{\mu\nu} = J^{\nu} \qquad v^{j} = u^{i}/u^{t}$$

$$b^{\mu} \equiv F^{*\mu\nu} u_{\nu} = \frac{1}{2} \varepsilon^{\mu\nu\kappa\lambda} F_{\kappa\lambda} u_{\nu} \qquad F^{*\mu\nu} = b^{\mu} u^{\nu} - b^{\nu} u^{\mu}$$

$$b^{\mu}u_{\mu} = 0$$
  $B^{i} \equiv F^{*it}$   $b^{t} = B^{i}u^{\mu}g_{i\mu}$   $b^{i} = \frac{1}{u^{t}}\left(B^{i} + b^{t}u^{i}\right)$ 

$$\partial_t \left( \sqrt{-g} B^i \right) = -\partial_j \left[ \sqrt{-g} \left( B^j v^i - B^i v^j \right) \right] \qquad \partial_j \left( \sqrt{-g} B^j \right) = 0$$

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$$F^{\mu\nu}u_{\mu} = 0 \qquad \nabla_{\mu}F^{*\mu\nu} = 0 \qquad \nabla_{\mu}F^{\mu\nu} = J^{\nu} \qquad v^{j} = u^{i}/u^{t}$$

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$$\begin{aligned}
\nu &= i \\
F^{\mu\nu}u_{\mu} &= 0 \qquad \nabla_{\mu}F^{*\mu\nu} = 0 \qquad \nabla_{\mu}F^{\mu\nu} = J^{\nu} \qquad v^{j} = u^{i}/u^{t} \\
b^{\mu} &\equiv F^{*\mu\nu}u_{\nu} &= \frac{1}{2}\varepsilon^{\mu\nu\kappa\lambda}F_{\kappa\lambda}u_{\nu} \qquad F^{*\mu\nu} = b^{\mu}u^{\nu} - b^{\nu}u^{\mu} \\
b^{\mu}u_{\mu} &= 0 \qquad B^{i} \equiv F^{*it} \qquad b^{t} = B^{i}u^{\mu}g_{i\mu} \qquad b^{i} = \frac{1}{u^{t}}\left(B^{i} + b^{t}u^{i}\right) \\
\overline{\partial_{t}\left(\sqrt{-g}B^{i}\right)} &= -\partial_{j}\left[\sqrt{-g}\left(B^{j}v^{i} - B^{i}v^{j}\right)\right] \qquad \partial_{j}\left(\sqrt{-g}B^{j}\right) = 0
\end{aligned}$$

$$\nu = t$$

$$F^{\mu\nu}u_{\mu} = 0 \qquad \nabla_{\mu}F^{*\mu\nu} = 0 \qquad \nabla_{\mu}F^{\mu\nu} = J^{\nu} \qquad v^{j} = u^{i}/u^{t}$$

$$b^{\mu} \equiv F^{*\mu\nu}u_{\nu} = \frac{1}{2}\varepsilon^{\mu\nu\kappa\lambda}F_{\kappa\lambda}u_{\nu} \qquad F^{*\mu\nu} = b^{\mu}u^{\nu} - b^{\nu}u^{\mu}$$

$$b^{\mu}u_{\mu} = 0 \qquad B^{i} \equiv F^{*it} \qquad b^{t} = B^{i}u^{\mu}g_{i\mu} \qquad b^{i} = \frac{1}{u^{t}}\left(B^{i} + b^{t}u^{i}\right)$$

$$\partial_{t}\left(\sqrt{-g}B^{i}\right) = -\partial_{j}\left[\sqrt{-g}\left(B^{j}v^{i} - B^{i}v^{j}\right)\right] \qquad \partial_{j}\left(\sqrt{-g}B^{j}\right) = 0$$

$$T_{\rm MHD}^{\mu\nu} = \left(\rho + \rho\epsilon + P + b^2\right) u^{\mu} u_{\nu} + \left(P + \frac{1}{2}b^2\right) \delta^{\mu}{}_{\nu} - b^{\mu} b_{\nu}$$

 $\nabla_{\mu}T^{\mu}{}_{\nu}=0$ 

$$\partial_t \sqrt{-g} \begin{bmatrix} \rho u^t \\ T^t{}_{\mu} \\ B^i \end{bmatrix} + \partial_j \sqrt{-g} \begin{bmatrix} \rho u^j \\ T^j{}_{\mu} \\ B^j v^i - B^i v^j \end{bmatrix} = \sqrt{-g} \begin{bmatrix} 0 \\ T^{\alpha}{}_{\beta} \Gamma^{\beta}{}_{\alpha\mu} \\ 0 \end{bmatrix}$$
$$\partial_t \left(\sqrt{-g} \mathbf{q}\right) + \partial_j \left(\sqrt{-g} \mathbf{F}^j\right) = \mathbf{S}(\mathbf{q}, g_{\mu\nu})$$
$$\partial_j \left(\sqrt{-g} B^j\right) = 0$$

#### **Non-conservative Methods**

 $\partial_t \mathbf{q} + \partial_i \mathbf{f}^i = \mathbf{S}(\mathbf{q}, \partial_\mu q)$ 

Experienced methods from hyrdro. simulations;

- Excellent for smooth flows;
- + Computationally efficient;

Use of upwind, monotonic methods for advection helps w/ shocks;

Requires use of artificial viscosity,  $P \rightarrow P + Q$ ;

Still problems near shocks, especially as  $v \rightarrow 1$ ;

Norman and Winkler, in Astrophys. Radiation Hydro., 449 (1986)

# **ZEUS-like: FD/CT/MOC-CT Methods**

FD = Finite Difference , MOC = Method of Characteristics CT = Constrained Transport

- Wilson, in 7th Texas Symp. on Rel. Astrophys., 1975. [MHD, Schwarz. Accretion]
- Hawley, Smarr, Wilson, ApJ 277, 296 (1984). [Hydro. Eq.s]
- Hawley, Smarr, Wilson, ApJS 55, 211, (1984). [Hydro. Tests, Kerr Accretion]
- Evans and Hawley, ApJ 332, 659 (1988). [CT, 2D MHD, Schwarzschild Accretion]
- Stone and Norman, *ApJS* **80**, 791 (1992). [ZEUS-2D, MOC-CT]
- ZEUS Code webpage, http://www.astro.princeton.edu/~jstone/zeus.html
- Hawley, Stone, Comput. Phys. Commun. 89, 127 (1995). [MOC-CT]
- De Villiers and Hawley, ApJ 589, 458 (2003). [3D MHD, Kerr Accretion]

# **De Villiers and Hawley 2003 (DH)**

Non-conservative scheme:

$$\partial_t \mathbf{q} + \partial_i \left[ v^i \mathbf{G}(\mathbf{q}, g_{\mu\nu}) \right] = \mathbf{S}(\mathbf{q}, \partial_\mu \mathbf{q}, g^{\mu\nu}, \partial_\alpha g^{\mu\nu})$$

• Evolution is broken down into several sub-steps:  $\partial_t \mathbf{q} = L(\mathbf{q})$ 

 $\mathbf{MOC} - \mathbf{CT} : \text{Finds } b^{\mu}$   $\mathbf{q}_{1} = \mathbf{q}_{0} + \Delta t L_{0}(\mathbf{q}_{0}) : \text{Transport } L_{0} \propto \partial_{i}(\sqrt{\gamma}v^{i}H), H = \{D, E, S_{j}\}$  $\mathbf{q}_{2} = \mathbf{q}_{1} + \Delta t L_{1}(\mathbf{q}_{1}) : \text{Source } L_{1} \propto \partial_{\mu}\{W, P, g_{\nu\lambda}, b^{\nu}\}, \mathbf{q}$ 

- Staggered mesh: vectors at cell faces , scalars at cell centers;
- New version of MOC-CT for  $\partial_i B^i = 0$ ;
- Full 3D MHD in Boyer-Lindquist coordinates;
- $L_0$  found via monotonic upwind scheme (van Leer 1977);

#### **Conservative Methods: Finite Volume**

 $\partial_t \mathbf{q} + \partial_x \mathbf{f} = \mathbf{S}(\mathbf{q})$ 

$$\bar{\mathbf{q}}_{j}^{n+1} - \bar{\mathbf{q}}_{j}^{n} = -\Delta t \left( \mathbf{F}_{j+1/2} - \mathbf{F}_{j-1/2} \right)^{n+1/2} + \Delta t \, \bar{\mathbf{S}}_{j}^{n+1/2}$$





 $\partial_t \mathbf{q} + \partial_i \mathbf{f}^i = \mathbf{S}(\mathbf{q})$ 

Assume piecewise-constant data,

 $\mathbf{q}\to \mathbf{\bar{q}}$ 



$$\partial_t \mathbf{q} + \partial_i \mathbf{f}^i = \mathbf{S}(\mathbf{q})$$

- Assume piecewise-constant data,
    $\mathbf{q} \to \overline{\mathbf{q}}$  For higher resolution.
  - For higher resolution, interpolate for  $\bar{\mathbf{q}}^L$  and  $\bar{\mathbf{q}}^R$



 $\partial_t \mathbf{q} + \partial_i \mathbf{f}^i = \mathbf{S}(\mathbf{q})$ 

- Assume piecewise-constant data,
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- For higher resolution, interpolate for  $\bar{\mathbf{q}}^L$  and  $\bar{\mathbf{q}}^R$
- Need to use monotonic (aka slope-limiting) interpolation;



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#### **Riemann Problem**



 $\ensuremath{\,{\rm \hspace{-.025cm}{\rm \hspace{-.025cm}{\rm Find}}}}\xspace {\rm \hspace{-.025cm}{\rm q}}(x,t)$  given

$$\partial_t \mathbf{q} + \partial_x \mathbf{f} = 0$$
$$\mathbf{q}(x, t = 0) = \begin{cases} \mathbf{q}^L & \text{for } x < 0\\ \mathbf{q}^R & \text{for } x > 0 \end{cases}$$

• Riemann solution  $\Rightarrow \mathbf{F}^{n+1/2}$ .

### **Hydrodynamic Riemann Solution**



# **MHD Riemann Solution**



 $F^{L,R}$  = Fast magnetosonic wave  $S^{L,R}$  = Slow magnetosonic wave

 $A^{L,R}$  = Alfvenic wave

C =Contact Discontinuity

#### **Approximate Riemann Solvers: HLL**

 $\partial_t \mathbf{q} + \mathbf{A}^i \partial_i \mathbf{q} = 0$ 



$$\mathbf{F}_{j+1/2}^{n+1/2} = \begin{cases} \mathbf{f}(\mathbf{q}^{L}) & \text{if } 0 \ge H^{L} \\ \frac{1}{\left(H^{R} - H^{L}\right)} \left[H^{R} \mathbf{f}^{L} - H^{L} \mathbf{f}^{R} + H^{L} H^{R} \left(\mathbf{q}^{R} - \mathbf{q}^{L}\right)\right] & \text{if } H^{L} \le 0 \le H^{R} \\ \mathbf{f}(\mathbf{q}^{R}) & \text{if } H^{R} \le 0 \end{cases}$$

# **Approximate Riemann Solvers: HLLC**



$$\mathbf{F}_{j+1/2}^{n+1/2} = \begin{cases} \mathbf{f}(\mathbf{q}^{L}) & \text{if } 0 \ge H^{L} \\ \mathbf{f}(\mathbf{q}^{L}) + H^{L} \left(\mathbf{q}^{L*} - \mathbf{q}^{L}\right) & \text{if } H^{L} \le 0 \le H^{*} \\ \mathbf{f}(\mathbf{q}^{R}) + H^{R} \left(\mathbf{q}^{R*} - \mathbf{q}^{R}\right) & \text{if } H^{L} \le 0 \le H^{*} \\ \mathbf{f}(\mathbf{q}^{R}) & \text{if } H^{R} \le 0 \end{cases}$$

### **Magnetized Bondi Flow**



### **Gammie Inflow**

Steady-state, equatorial, magnetized inflow in Kerr inside marginally stable orbit;



#### • Komissarov, MNRAS 303, 343 (1999).



#### Rarefaction



# **Qualities of Conservative GRMHD Schemes**

- Improved behavior in shock tests
- Equivalent behavior in relativistic cases
- Better behavior for ultra-relativistic flows
- Still developmental
- Worse behavior in "floored" regions
- Worse behavior when  $P_{\rm mag} \gg P$
- - $\Rightarrow$  Slower code!

## **Other Schemes**

- Del Zanna et al., AA **400**, 397 (2003).
  - 3rd-order CENO with HLL
  - SRMHD
- Balsara, ApJS 132, 83 (2001).
  - Roe-type Approx. Riemann Solver
  - Interpolates characteristic variables
  - SRMHD
- ATHENA, http://www.astro.princeton.edu/ jstone/athena.html
  - Roe-type Approx. Riemann Solver
  - Not relativistic

# **Maintianing the Divergence Constraint**



- Toth, J. Comp. Phys., 161, 605 (2000).
   TVD-Lax-Friedrich
- $\partial_i B^i \neq 0$  leads to:
  - Non-perpendicular Lorentz forces to  $B^i$
  - Inconsistency in MHD
  - Instabilities and spurious effects

$$\mathcal{E}^z = v^x B^y - v^y B^x = f^x$$

- CT : Evans and Hawley 1988
- MOC-CT: Hawley and Stone 1995
- MOC-CT2: De Villiers and Hawley 2003



• Field-CT: Interp. predicted  $B^i$  and  $v^i$  for  $\mathcal{E}_{j+1}^{n+1/2}$ ;



- Field-CT: Interp. predicted  $B^i$  and  $v^i$  for  $\mathcal{E}_{j+1}^{n+1/2}$ ;
- Flux-CT: Interp.  $f^{i^*}$  and  $f^{i^n}$  for  $\mathcal{E}_{j+1/2}^{n+1/2}$ ;

v×B	<sup>↑</sup> B <sup>y</sup>	v×B
B <sup>x</sup> →	∇. <b>B</b>	B <sup>x</sup> →
v×B	By	v ×B

- Field-CT: Interp. predicted  $B^i$  and  $v^i$  for  $\mathcal{E}_{j+1}^{n+1/2}$ ;
- Flux-CT: Interp.  $f^{i^*}$  and  $f^{i^n}$  for  $\mathcal{E}_{j+1/2}^{n+1/2}$ ;

• Field-CD: 
$$\mathcal{E}_j^{n+1/2} = \frac{1}{2} \left( \mathcal{E}_j^n + \mathcal{E}_j^* \right);$$



- Field-CT: Interp. predicted  $B^i$  and  $v^i$  for  $\mathcal{E}_{j+1}^{n+1/2}$ ;
- Flux-CT: Interp.  $f^{i^*}$  and  $f^{i^n}$  for  $\mathcal{E}_{j+1/2}^{n+1/2}$ ;
- Field-CD:  $\mathcal{E}_j^{n+1/2} = \frac{1}{2} \left( \mathcal{E}_j^n + \mathcal{E}_j^* \right);$
- Flux-CD:  $f^{i^*}$  for  $\mathcal{E}_j^{n+1/2}$ ;

K. G. Powell, P. L. Roe, et al., *J. Comput. Phys.* 154, 284 (1999).K. G. Powell, ICASE Report No. 94-24, Langley, VA, 1994.

- MHD equations can be derived w/o assuming constraint ⇒ ∃ source terms  $\propto \partial_i B^i$ ;
- With  $\partial_i B^i$  source terms, conserves divergence constraint along flow lines:  $\partial_t (\partial_i B^i) + \partial_j (v^j \partial_i B^i) = 0$ 
  - Supposed to preserve initially constrained data along flows;
  - + Any monopoles are transported away *hopefully* off the grid;
  - Increases robustness, G. Tóth and D. Odstrěil, *J. Comput. Phys.* **128**, 82 (1996).
  - Formulation becomes non-conservative  $\Rightarrow$  problems near strong shocks;

# **Divergence Cleaning Schemes**

J. U. Brackbill and D. C. Barnes, *J. Comput. Phys.* 35, 426 (1980).
C.-D. Munz, *J. Comput. Phys.* 161, 484 (2000).
A. Dedner, et al., *J. Comput. Phys.* 175, 645 (2002).
S. S. Komissarov, Appendix C of *astro-ph/0402403*.

$$\partial_t B^i - \partial_j \left( v^i B^j - v^j B^i + g^{ij} \Psi \right) = 0$$
$$\mathcal{D}(\Psi) + \partial_i B^i = 0$$
$$\Rightarrow \partial_t \mathcal{D}(\Psi) = \partial_i \partial^i \Psi$$

$$\mathcal{D}(\Psi) = 0 \qquad \Rightarrow \qquad \partial_i \partial^i \Psi = 0 \qquad \text{Elliptic} \\ \mathcal{D}(\Psi) = \frac{1}{p} \Psi \qquad \Rightarrow \qquad \partial_t \Psi = p \ \partial_i \partial^i \Psi \qquad \text{Parabolic} \\ \mathcal{D}(\Psi) = \frac{1}{h^2} \ \partial_t \Psi \qquad \Rightarrow \qquad \partial_{tt} \Psi = h^2 \ \partial_i \partial^i \Psi \qquad \text{Hyperbolic} \\ \mathcal{D}(\Psi) = \frac{1}{h^2} \ \partial_t \Psi + \frac{1}{p^2} \ \Psi \qquad \Rightarrow \qquad \partial_{tt} \Psi + \frac{h^2}{p^2} \ \partial_t \Psi = h^2 \ \partial_i \partial^i \Psi \qquad \text{Mixed}$$

#### **Discretization Differences in Constraint**

#### TABLE IV

#### Divergence B in the 2D Rotated Shock Tube Test

	$  abla \cdot .$	$\boldsymbol{B}_{j,k}$	$ \nabla \cdot \boldsymbol{B}_{j+1/2,k+1/2} $	
	Max	Avrg	Max	Avrg
Base scheme	141.5	3.43	48.9	3.27
8-wave	142.5	3.62	57.0	1.91
Projection	0.3	0.01	130.9	4.73
Field-CD	$10^{-12}$	$10^{-13}$	84.2	3.81
Flux-CD	$10^{-12}$	$10^{-13}$	68.5	3.91
Field-CT	65.9	5.63	$10^{-12}$	$10^{-13}$
Flux-CT	73.5	2.09	$10^{-12}$	$10^{-13}$
Tr-flux-CT	102.8	2.95	$10^{-12}$	10 <sup>-13</sup>

#### **2D Shock Tube Test**



# TABLE IIINumerical Errors in the 2D Shock Tube Test for $\alpha = 63.4^{\circ}$ and N = 256

	$\delta  ho$	$\delta v_{\parallel}$	$\delta v_\perp$	$\delta p$	$\delta B_{\parallel}$	$\delta B_{\perp}$	$\bar{\delta}$
Field-CD	0.0074	0.0175	0.0936	0.0052	0.0046	0.0102	0.0231
Flux-CD	0.0075	0.0175	0.0965	0.0052	0.0036	0.0107	0.0235
Projection	0.0076	0.0177	0.0948	0.0055	0.0062	0.0093	0.0235
Flux-CT	0.0075	0.0176	0.0996	0.0052	0.0016	0.0098	0.0235
Base scheme	0.0075	0.0178	0.1006	0.0055	0.0037	0.0078	0.0238
Tr-flux-CT	0.0075	0.0177	0.1020	0.0054	0.0020	0.0089	0.0239
Field-CT	0.0075	0.0174	0.1214	0.0059	0.0043	0.0178	0.0291
8-wave	0.0076	0.0180	0.1027	0.0056	0.0413	0.0092	0.0307

# **Orzag-Tang Vortex**



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